



# Performance comparison between hybridizable DG and classical DG methods for elastic waves simulation in harmonic domain

M. Bonnasse-Gahot<sup>1,2</sup>, H. Calandra<sup>3</sup>, J. Diaz<sup>1</sup> and S. Lanteri<sup>2</sup>

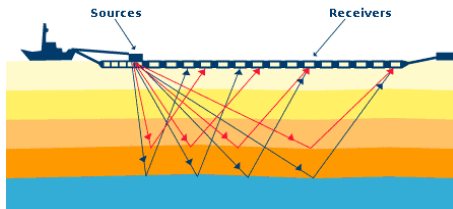
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<sup>2</sup> INRIA Sophia-Antipolis-Méditerranée, team-project Nachos

<sup>3</sup> TOTAL Exploration-Production

# Motivation

## Examples of seismic applications



# Motivation

Imaging method : the full wave inversion

- ▶ Iterative procedure
- ▶ Inverse problem requiring to solve a **lot of forward problems**

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- ▶ Time-domain : **imaging condition complicated** but **low computational cost**
- ▶ Harmonic-domain : **imaging condition simple** but **huge computational cost**

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## Imaging method : the full wave inversion

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- ▶ Inverse problem requiring to solve a **lot of forward problems**

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## Forward problem of the inversion process

- ▶ Elastic wave propagation in harmonic domain : **Helmholtz equation**
- ▶ Reduction of the size of the linear system

# Motivation

## Seismic imaging in heterogeneous complex media

- ▶ Complex topography
- ▶ High heterogeneities

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Use of unstructured meshes with FE methods

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## Use of unstructured meshes with FE methods

### DG method

- ▶ Flexible choice of interpolation orders ( $p$  – *adaptativity*)
- ▶ Highly parallelizable method
- ▶ Increased computational cost as compared to classical FEM



# Motivation

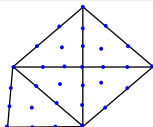
## Seismic imaging in heterogeneous complex media

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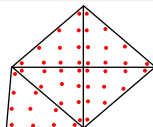
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## DG method

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DOF of classical FEM



DOF of DGM

# Motivation

## Objective of this work

- ▶ Development of an hybridizable DG (HDG) method
- ▶ Comparison with a reference method : a standard nodal DG method

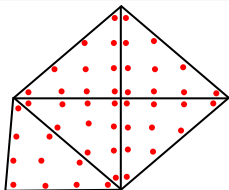


FIGURE : Degrees of freedom of DGM

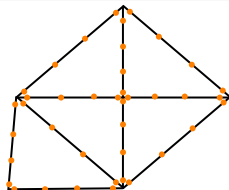


FIGURE : Degrees of freedom of HDGM

# HDG methods

## HDG methods

- ▶ B. Cockburn, J. Gopalakrishnan, R. Lazarov *Unified hybridization of discontinuous Galerkin, mixed and continuous Galerkin methods for second order elliptic problems*, SIAM Journal on Numerical Analysis, Vol. 47 (2009)
- ▶ S. Lanteri, L. Li, R. Perrussel, *Numerical investigation of a high order hybridizable discontinuous Galerkin method for 2d time-harmonic Maxwell's equations*, COMPEL, Vol. 32 (2013) (time-harmonic domain)
- ▶ N.C. Nguyen, J. Peraire, B. Cockburn, *High-order implicit hybridizable discontinuous Galerkin methods for acoustics and elastodynamics*, J. of Comput. Physics, Vol. 230 (2011) (time domain for seismic applications)

# Contents

2D Helmholtz elastic equations

Notations and definitions

Hybridizable Discontinuous Galerkin method

Numerical results

Conclusions-Perspectives

## 2D Helmholtz elastic equations

### First order formulation of Helmholtz wave equations

$$\mathbf{x} = (x, y) \in \Omega \subset \mathbb{R}^2,$$

$$\begin{cases} i\omega \rho(\mathbf{x}) \mathbf{v}(\mathbf{x}) = \nabla \cdot \underline{\underline{\sigma}}(\mathbf{x}) + \mathbf{f}_s(\mathbf{x}) \\ i\omega \underline{\underline{\sigma}}(\mathbf{x}) = \underline{\underline{C}}(\mathbf{x}) \underline{\underline{\varepsilon}}(\mathbf{v}(\mathbf{x})) \end{cases}$$

- ▶ Free surface condition :  $\underline{\underline{\sigma}} \mathbf{n} = 0$  on  $\Gamma_f$
- ▶ Absorbing boundary condition :  $\underline{\underline{\sigma}} \mathbf{n} = v_p(\mathbf{v} \cdot \mathbf{n})\mathbf{n} + v_s(\mathbf{v} \cdot \mathbf{t})\mathbf{t}$  on  $\Gamma_a$
- ▶  $\mathbf{v}$  : velocity vector
- ▶  $\underline{\underline{\sigma}}$  : stress tensor
- ▶  $\underline{\underline{\varepsilon}}$  : strain tensor

## 2D Helmholtz elastic equations

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- 
- |   |  |
|---|--|
| ▶ $\rho$ : mass density   | ▶ $v_p$ : P-wave velocity                                      |
| ▶ $\underline{\underline{C}}$ : tensor of elasticity coefficients | ▶ $v_s$ : S-wave velocity                                      |
|   | ▶ $\mathbf{f}_s$ : source term, $\mathbf{f}_s \in L^2(\Omega)$ |

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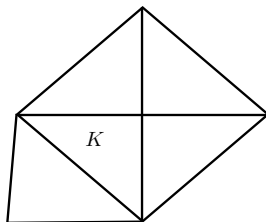
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# Notations and definitions

## Notations

- $\mathcal{T}_h$  mesh of  $\Omega$  composed of triangles  $K$

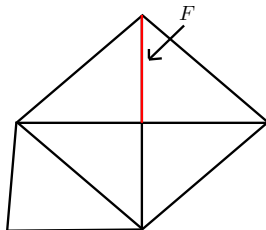




# Notations and definitions

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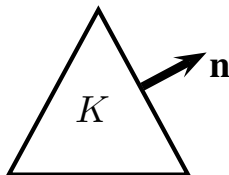
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- ▶  $\mathcal{F}_h$  set of all faces  $F$  of  $\mathcal{T}_h$



# Notations and definitions

## Notations

- ▶  $\mathcal{T}_h$  mesh of  $\Omega$  composed of triangles  $K$
- ▶  $\mathcal{F}_h$  set of all faces  $F$  of  $\mathcal{T}_h$
- ▶  $\mathbf{n}$  the normal outward vector of an element  $K$



# Notations and definitions

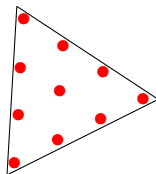
## Approximations spaces

- ▶  $P_p(K)$  set of polynomials of degree at most  $p$  on  $K$

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## Approximations spaces

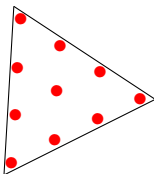
- ▶  $P_p(K)$  set of polynomials of degree at most  $p$  on  $K$
- ▶  $\mathbf{V}_h^p = \{\mathbf{v} \in (L^2(\Omega))^2 : \mathbf{v}|_K \in \mathbf{V}^p(K) = (P_p(K))^2, \forall K \in \mathcal{T}_h\}$



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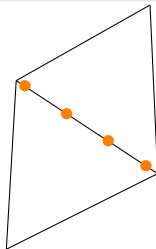
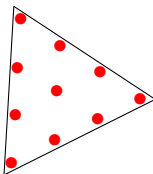
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- ▶  $\Sigma_h^p = \{\underline{\underline{\sigma}} \in (L^2(\Omega))^3 : \underline{\underline{\sigma}}|_K \in \Sigma^p(K) = (P_p(K))^3, \forall K \in \mathcal{T}_h\}$



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- ▶  $\mathbf{M}_h = \{\eta \in (L^2(\mathcal{F}_h))^2 : \eta|_F \in (P_p(F))^2, \forall F \in \mathcal{F}_h\}$



# Notations and definitions

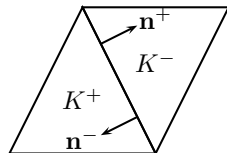
## Definitions

- ▶ Jump  $[[\cdot]]$  of a vector  $\mathbf{v}$  through  $F$  :

$$[[\mathbf{v}]] = \mathbf{v}^+ \cdot \mathbf{n}^+ + \mathbf{v}^- \cdot \mathbf{n}^- = \mathbf{v}^+ \cdot \mathbf{n}^+ - \mathbf{v}^- \cdot \mathbf{n}^+$$

- ▶ Jump of a tensor  $\underline{\underline{\sigma}}$  through  $F$  :

$$[[\underline{\underline{\sigma}}]] = \underline{\underline{\sigma}}^+ \mathbf{n}^+ + \underline{\underline{\sigma}}^- \mathbf{n}^- = \underline{\underline{\sigma}}^+ \mathbf{n}^+ - \underline{\underline{\sigma}}^- \mathbf{n}^+$$



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# HDG formulation of the equations

## Local HDG formulation

$$\begin{cases} i\omega\rho\mathbf{v} - \nabla \cdot \underline{\underline{\sigma}} &= 0 \\ i\omega\underline{\underline{\sigma}} - \underline{\underline{C}}\varepsilon(\mathbf{v}) &= 0 \end{cases}$$

# HDG formulation of the equations

## Local HDG formulation

$$\left\{ \begin{array}{l} \int_K i\omega \rho^{\text{blue}} \mathbf{v}^K \cdot \mathbf{w} + \int_K \underline{\underline{\sigma}}^K : \nabla \mathbf{w} - \int_{\partial K} \widehat{\underline{\underline{\sigma}}}^{\partial K} \cdot \mathbf{n} \cdot \mathbf{w} = 0 \\ \int_K i\omega \underline{\underline{\sigma}}^K : \underline{\underline{\xi}} + \int_K \mathbf{v}^K \cdot \nabla \cdot (\underline{\underline{C}}^K \underline{\underline{\xi}}) - \int_{\partial K} \widehat{\mathbf{v}}^{\partial K} \cdot \underline{\underline{C}}^K \underline{\underline{\xi}} \cdot \mathbf{n} = 0 \end{array} \right.$$

$\widehat{\underline{\underline{\sigma}}}^K$  and  $\widehat{\mathbf{v}}^K$  are numerical traces of  $\underline{\underline{\sigma}}^K$  and  $\mathbf{v}^K$  respectively on  $\partial K$

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## Local HDG formulation

$$\begin{cases} \int_K i\omega \rho^K \mathbf{v}^K \cdot \mathbf{w} + \int_K \underline{\underline{\sigma}}^K : \nabla \mathbf{w} - \int_{\partial K} \widehat{\underline{\underline{\sigma}}}^{\partial K} \cdot \mathbf{n} \cdot \mathbf{w} = 0 \\ \int_K i\omega \underline{\underline{\sigma}}^K : \underline{\underline{\xi}} + \int_K \mathbf{v}^K \cdot \nabla \cdot (\underline{\underline{C}}^K \underline{\underline{\xi}}) - \int_{\partial K} \widehat{\mathbf{v}}^{\partial K} \cdot \underline{\underline{C}}^K \underline{\underline{\xi}} \cdot \mathbf{n} = 0 \end{cases}$$

We define :

$$\begin{aligned} \widehat{\mathbf{v}}^F &= \lambda^F, & \forall F \in \mathcal{F}_h, \\ \widehat{\underline{\underline{\sigma}}}^{\partial K} \cdot \mathbf{n} &= \underline{\underline{\sigma}}^K \cdot \mathbf{n} - \tau \mathbf{l}(\mathbf{v}^K - \lambda^{\partial K}), & \text{on } \partial K \end{aligned}$$

where  $\tau$  is the stabilization parameter ( $\tau > 0$ )

# HDG formulation of the equations

## Local HDG formulation

We replace  $\hat{\mathbf{v}}^K$  and  $(\hat{\underline{\underline{\sigma}}}^K \cdot \mathbf{n})$  by their definitions into the local equations

$$\left\{ \begin{array}{l} \int_K i\omega \rho^K \mathbf{v}^K \cdot \mathbf{w} + \int_K \underline{\underline{\sigma}}^K : \nabla \mathbf{w} - \int_{\partial K} \underline{\underline{\sigma}}^K \cdot \mathbf{n} \cdot \mathbf{w} \\ \quad + \int_{\partial K} \tau \mathbf{l} \left( \mathbf{v}^K - \lambda^{\partial K} \right) \cdot \mathbf{w} = 0 \\ \int_K i\omega \underline{\underline{\sigma}}^K : \underline{\underline{\xi}} + \int_K \mathbf{v}^K \cdot \nabla \cdot \left( \underline{\underline{C}}^K \underline{\underline{\xi}} \right) - \int_{\partial K} \lambda^{\partial K} \cdot \underline{\underline{C}}^K \underline{\underline{\xi}} \cdot \mathbf{n} = 0 \end{array} \right.$$

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$$\left\{ \begin{array}{l} \int_K i\omega \rho^K \mathbf{v}^K \cdot \mathbf{w} - \int_K (\nabla \cdot \underline{\underline{\sigma}}^K) \cdot \mathbf{w} + \int_{\partial K} \tau \mathbf{l} (\mathbf{v}^K - \lambda^{\partial K}) \cdot \mathbf{w} = 0 \\ \int_K i\omega \underline{\underline{\sigma}}^K : \underline{\underline{\xi}} + \int_K \mathbf{v}^K \cdot \nabla \cdot (\underline{\underline{c}}^K \underline{\underline{\xi}}) - \int_{\partial K} \lambda^{\partial K} \cdot \underline{\underline{c}}^K \underline{\underline{\xi}} \cdot \mathbf{n} = 0 \end{array} \right.$$

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We define :

$$\underline{\underline{W}}^K = (\underline{v}_x^K, \underline{v}_z^K, \underline{\sigma}_{xx}^K, \underline{\sigma}_{zz}^K, \underline{\sigma}_{xz}^K)^T$$

$$\underline{\underline{\Lambda}} = (\underline{\Lambda}^{F_1}, \underline{\Lambda}^{F_2}, \dots, \underline{\Lambda}^{F_{n_f}})^T, \text{ where } n_f = \text{card}(\mathcal{F}_h)$$

## Discretization of the local HDG formulation

$$\underline{\mathbf{A}}^K \underline{\underline{W}}^K + \underline{\mathbf{C}}^K \underline{\underline{\Lambda}} = 0$$

# HDG formulation of the equations

## Transmission condition

In order to determine  $\lambda^K$ , the continuity of the normal component of  $\underline{\hat{\sigma}}^K$  is weakly enforced, rendering this numerical trace conservative :

$$\int_F \llbracket \underline{\hat{\sigma}}^K \cdot \mathbf{n} \rrbracket \cdot \eta = 0$$

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Replacing  $(\underline{\hat{\sigma}}^K \cdot \mathbf{n})$  and summing over all faces, the transmission condition becomes :

$$\sum_{K \in \mathcal{T}_h} \int_{\partial K} (\underline{\hat{\sigma}}^K \cdot \mathbf{n}) \cdot \eta - \sum_{K \in \mathcal{T}_h} \int_{\partial K} \tau \mathbf{l} (\mathbf{v}^K - \lambda^{\partial K}) \cdot \eta = 0$$



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## Discretization of the transmission condition

$$\sum_{K \in \mathcal{T}_h} [\mathbb{B}^K \underline{w}^K + \mathbb{L}^K \underline{\Lambda}] = 0$$

# HDG formulation of the equations

## Global HDG formulation

$$\left\{ \begin{array}{l} \int_K i\omega \underline{\rho}^K \underline{\mathbf{v}}^K \cdot \underline{\mathbf{w}} - \int_K (\nabla \cdot \underline{\underline{\underline{\sigma}}^K}) \cdot \underline{\mathbf{w}} + \int_{\partial K} \tau \mathbf{l} (\underline{\mathbf{v}}^K - \underline{\lambda}^{\partial K}) \cdot \underline{\mathbf{w}} = 0 \\ \int_K i\omega \underline{\underline{\underline{\sigma}}}^K : \underline{\underline{\underline{\xi}}} + \int_K \underline{\mathbf{v}}^K \cdot \nabla \cdot (\underline{\underline{\underline{C}}}^K \underline{\underline{\underline{\xi}}}) - \int_{\partial K} \underline{\lambda}^{\partial K} \cdot \underline{\underline{\underline{C}}}_K \underline{\underline{\underline{\xi}}} \cdot \underline{\mathbf{n}} = 0 \\ \sum_{K \in \mathcal{T}_h} \int_{\partial K} (\underline{\underline{\underline{\sigma}}}^K \cdot \underline{\mathbf{n}}) \cdot \underline{\eta} - \sum_{K \in \mathcal{T}_h} \int_{\partial K} \tau \mathbf{l} (\underline{\mathbf{v}}^K - \underline{\lambda}^{\partial K}) \cdot \underline{\eta} = 0 \end{array} \right.$$

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## Global HDG discretization

$$\left\{ \begin{array}{l} \underline{\mathbb{A}}^K \underline{\underline{w}}^K + \underline{\mathbb{C}}^K \underline{\underline{\Lambda}} = 0 \\ \sum_{K \in \mathcal{T}_h} [\underline{\mathbb{B}}^K \underline{\underline{w}}^K + \underline{\mathbb{L}}^K \underline{\underline{\Lambda}}] = 0 \end{array} \right.$$

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## Global HDG discretization

$$\left\{ \begin{array}{l} \underline{\mathbf{w}}^K = -(\underline{\mathbf{A}}^K)^{-1} \underline{\mathbb{C}}^K \underline{\underline{\Lambda}} \\ \sum_{K \in \mathcal{T}_h} [\underline{\mathbb{B}}^K \underline{\mathbf{w}}^K + \underline{\mathbb{L}}^K \underline{\underline{\Lambda}}] = 0 \end{array} \right.$$

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## Global HDG discretization

$$\sum_{K \in \mathcal{T}_h} [-\underline{\mathbf{B}}^K (\underline{\mathbf{A}}^K)^{-1} \underline{\mathbf{C}}^K + \underline{\mathbf{L}}^K] \underline{\underline{\Lambda}} = 0$$

# Main idea of the algorithm using the HDG formulation

---

1. Construction of the linear system  $\mathbf{M}\underline{\Lambda} = 0$

with  $\mathbf{M} = \sum_{K \in \mathcal{T}_h} \left[ -\mathbf{B}^K (\mathbf{A}^K)^{-1} \mathbf{C}^K + \mathbf{L}^K \right]$

**for**  $K = 1$  to  $Nb_{tri}$  **do**

    Compute matrices  $\mathbf{B}^K, (\mathbf{A}^K)^{-1}, \mathbf{C}^K$  and  $\mathbf{L}^K$

    Construction of the corresponding section of  $\mathbf{K}$

**end for**

---

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- 
1. Construction of the linear system  $\mathbf{M}\underline{\Lambda} = 0$
  2. Construction of the right hand side  $\mathbf{S}$
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  3. Resolution  $\mathbf{M}\underline{\Lambda} = \mathbf{S}$
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# Main idea of the algorithm using the HDG formulation

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1. Construction of the linear system  $\underline{\mathbf{M}}\underline{\Lambda} = 0$
  2. Construction of the right hand side  $\underline{\mathbf{S}}$
  3. Resolution  $\underline{\mathbf{M}}\underline{\Lambda} = \underline{\mathbf{S}}$
  4. Computation of the solutions of the initial problem

**for**  $K = 1$  to  $Nb_{tri}$  **do**  
     Compute  $\underline{\mathbf{W}}^K = -(\underline{\mathbf{A}}^K)^{-1}\underline{\mathbf{C}}^K\underline{\Lambda}$   
**end for**

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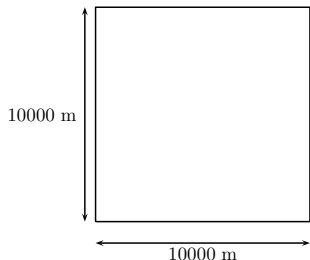
**Numerical results**

Plane wave in an homogeneous medium

Marmousi test-case

Conclusions-Perspectives

# Plane wave



Computational domain  $\Omega$   
setting

► Physical parameters :

- $\rho = 2000 \text{ kg.m}^{-3}$
- $\lambda = 16 \text{ GPa}$
- $\mu = 8 \text{ GPa}$

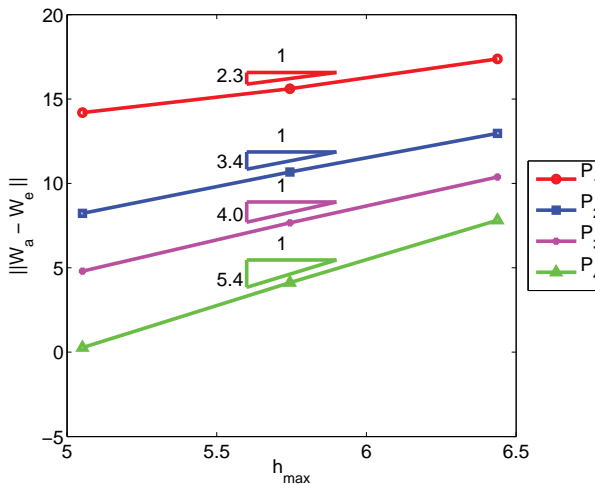
► Plane wave :

$$u = \nabla e^{i(k \cos \theta x + k \sin \theta y)}$$

$$\text{where } k = \frac{\omega}{v_p}$$

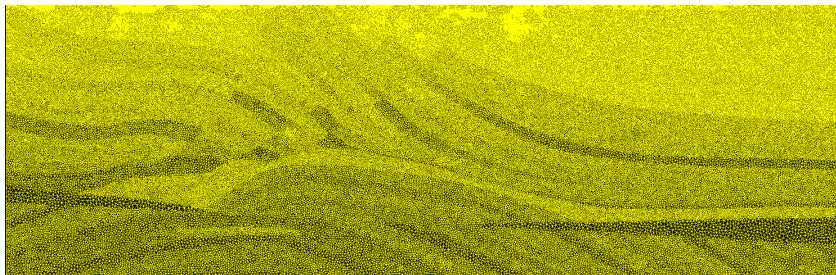
- $\theta = 0$
- Three meshes :
  - 3000 elements
  - 10000 elements
  - 45000 elements

# Plane wave



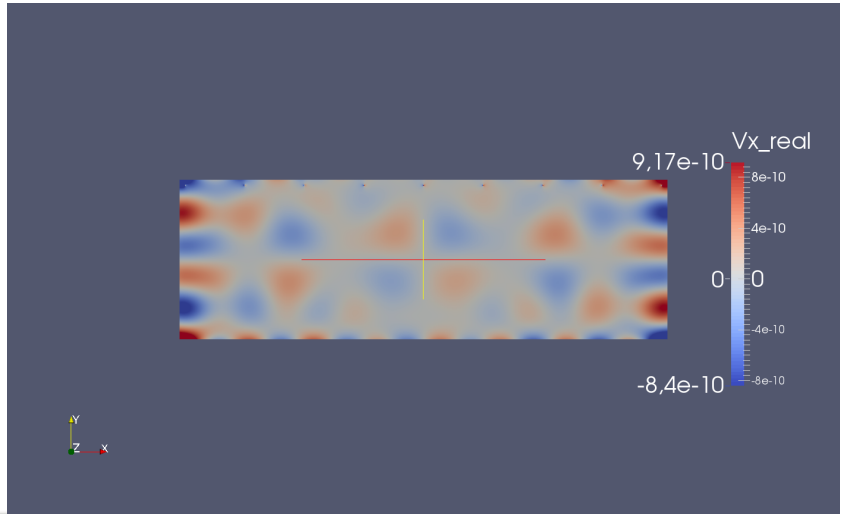
Convergence order of the HDG scheme

# Marmousi test-case



Computational domain  $\Omega$  composed of 235000 triangles

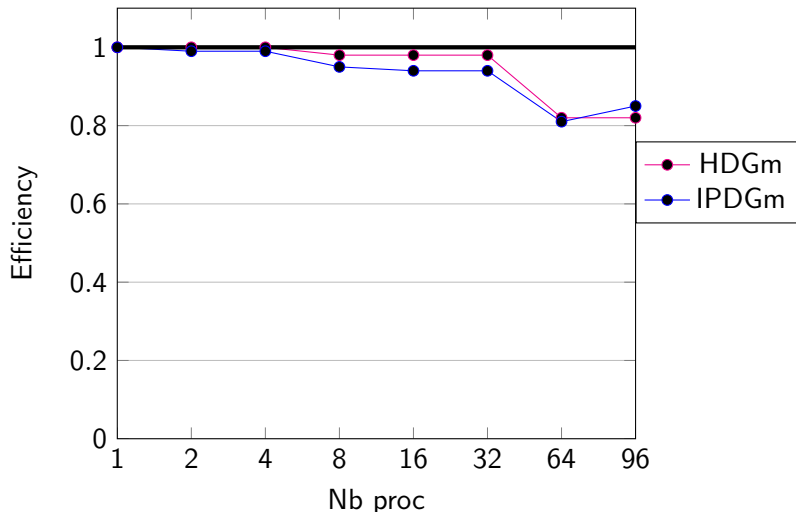
# Parallel results for the Marmousi test-case with the HDG-P3 scheme, $f = 2\text{Hz}$



# Characteristics of the computing processors used

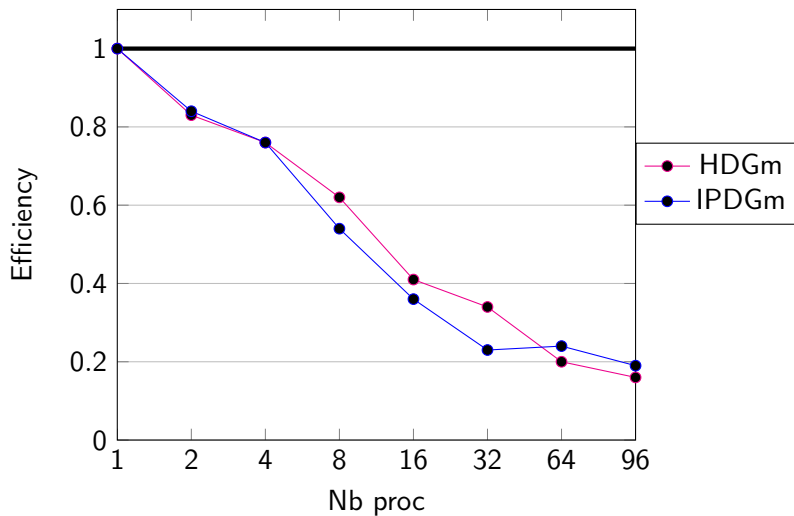
- **Plafrim** platform
- Hardware specification : 16 nodes, 12 cores by nodes
- Characteristics of computing nodes :
  - ▶ 2 Hexa-core Westmere Intel<sup>®</sup> Xeon<sup>®</sup> X5670
  - ▶ Frequency : 2,93 GHz
  - ▶ Cache L3 : 12 Mo
  - ▶ RAM : 96 Go
  - ▶ Infiniband DDR : 20Gb/s
  - ▶ Ethernet : 1Gb/s

# Efficiency of the parallelism of the global matrix construction

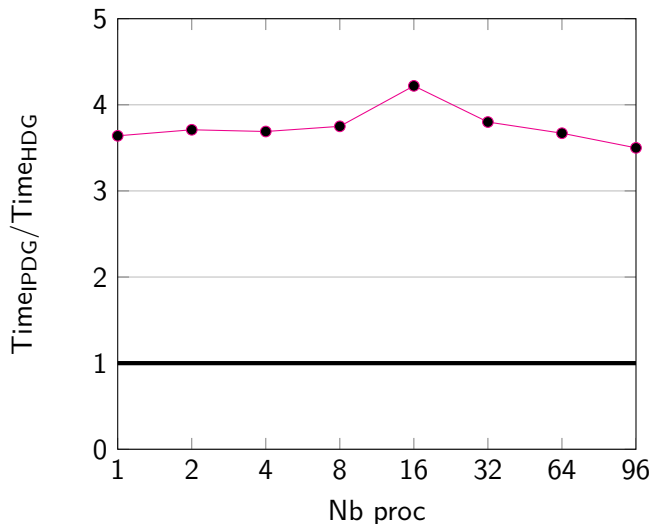




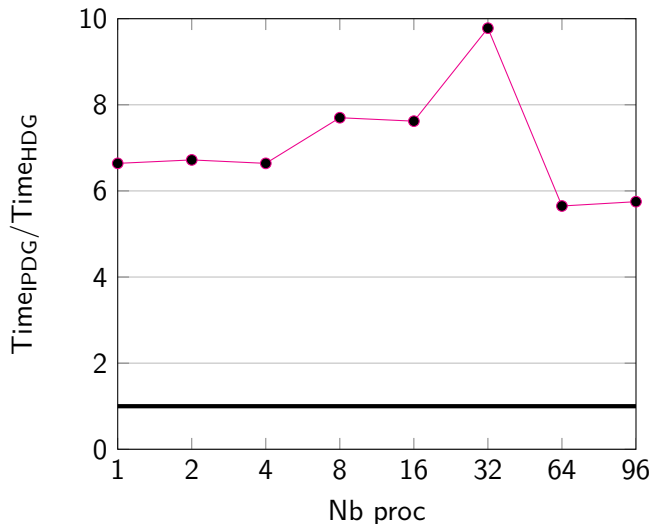
# Efficiency of the parallelism of the whole algorithm



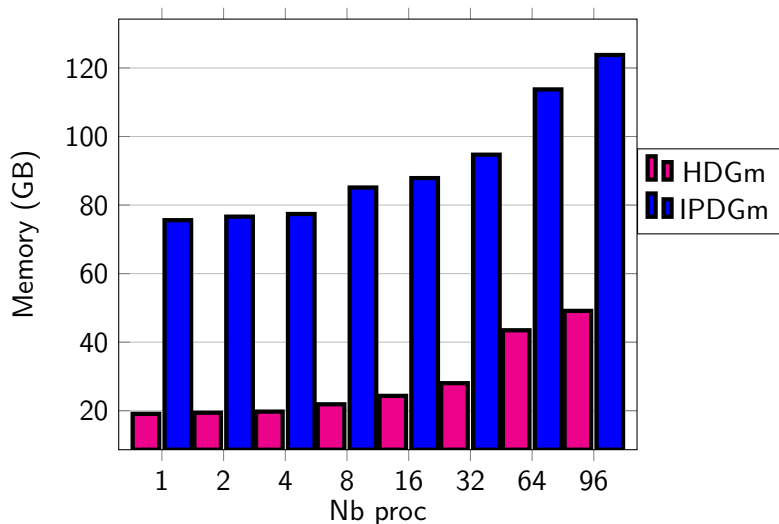
## Speed up for the global matrix construction



## Speed up (Total simulation time)



# Memory required (GB) for the simulation



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# Conclusions-Perspectives

## Conclusions

On a same mesh, with the HDG method :

- ▶ Memory gain
- ▶ Computational time gain

# Conclusions-Perspectives

## Conclusions

On a same mesh, with the HDG method :

- ▶ Memory gain
- ▶ Computational time gain

## Perspectives

- ▶ Develop 3D HDG formulation for Helmholtz equations
- ▶ Solution strategy for the HDG linear system

Thank you !

